



# Towards Robust Inference in Graphical Models

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# Beforehand

Towards  
Robust  
Inference in  
Graphical  
Models

Context

Problem  
statement

Proposed  
solution

Conclusion

- This is ongoing work
  - Speculative statements: \*
  - Unsubstantiated statements: \*
- Informal development
- Toy problems
- Feedback and collaboration welcome



# Outline

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- 1 What are we talking about?
- 2 So what is the problem?
- 3 What can we do about it?
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# Inference in Graphical Models

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- 2 components: model and evidence
- Modelling:
  - Define random variables and statistical relationships between them
  - Directed graph (Bayes network) or undirected graph (Markov network)
  - General framework
- Evidence
  - Typically measurements
- Inference: model + evidence  $\rightarrow$  answers to questions
  - 2 main flavours: variational and sampling-based
  - We focus on message passing (variational)

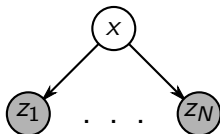


# Regression Example

Model:

$$p(x) = \mathcal{N}(\mu_x, \sigma_x^2)$$

$$z_i = x + \epsilon_i, \quad \epsilon_i \sim \mathcal{N}(0, \sigma_z^2), \quad i = 1, \dots, N$$



Question:

$$p(x|z_1, \dots, z_N)?$$



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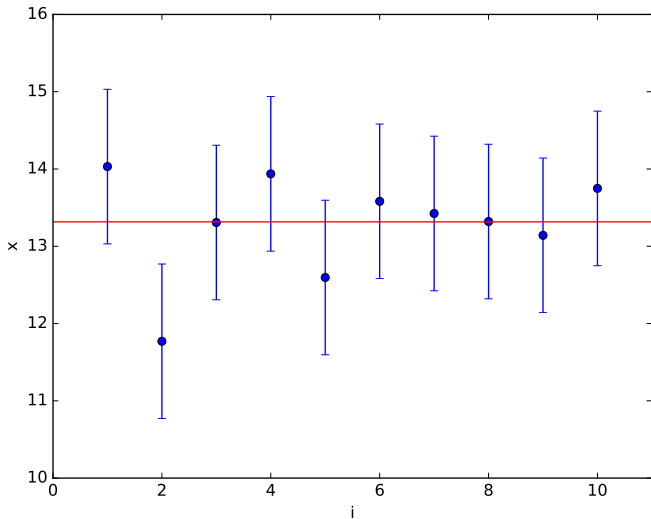
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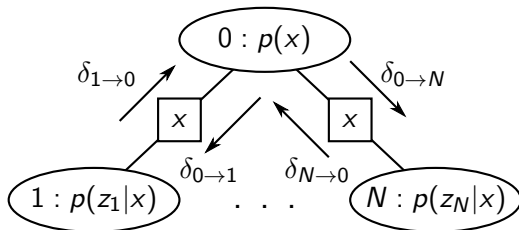
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# Regression Example

Inference:



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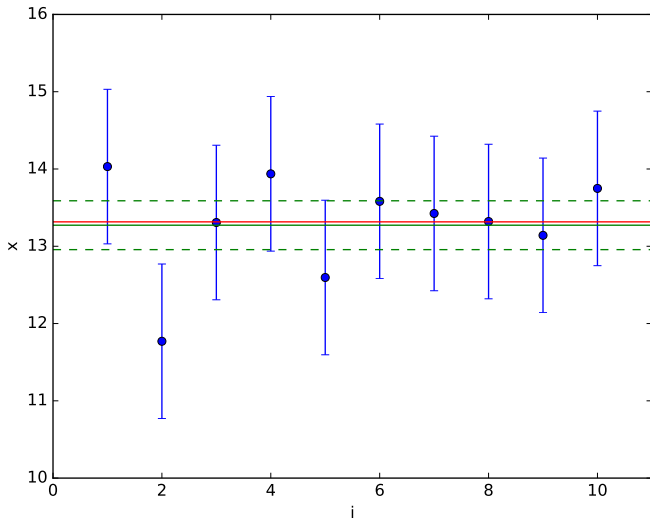
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# So what is the problem?

- Inference never produces correct answers
  - Models are never correct\*
  - Tractable inference require approximations
- Result:
  - Rubbish answers
  - Things break\*
- Existing approaches:
  - Full Bayesian approach
  - Model selection
- Disadvantages of existing approaches:
  - Require complex models
  - Expensive
  - They do not solve problem\*

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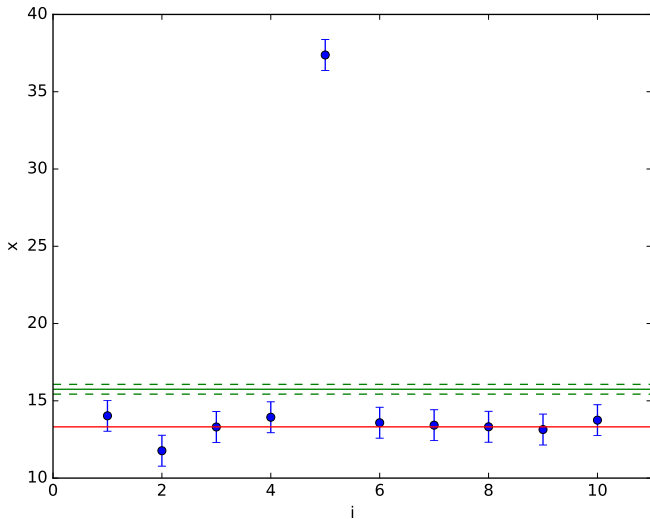
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# Quantifying Model Inconsistency

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- Bayesian surprise:

$$S(E, p(x)) \triangleq D_{KL}(p(x|E)||p(x))$$

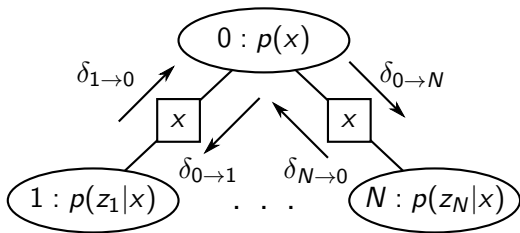
- *How much the evidence changed the prior belief*
- Properties:
  - Number between 0 and  $\infty$
  - Lower measurement likelihood  $\rightarrow$  higher surprise
  - Defined for most parametric distributions
  - For Gaussian measurement – scaled Mahalanobis distance squared



# Quantifying Model Inconsistency

- For regression example:

$$S_1 \triangleq S(z_1, \delta_{0 \rightarrow i}(x)) = D_{KL}(\beta(x) || \delta_{0 \rightarrow 1}(x))$$



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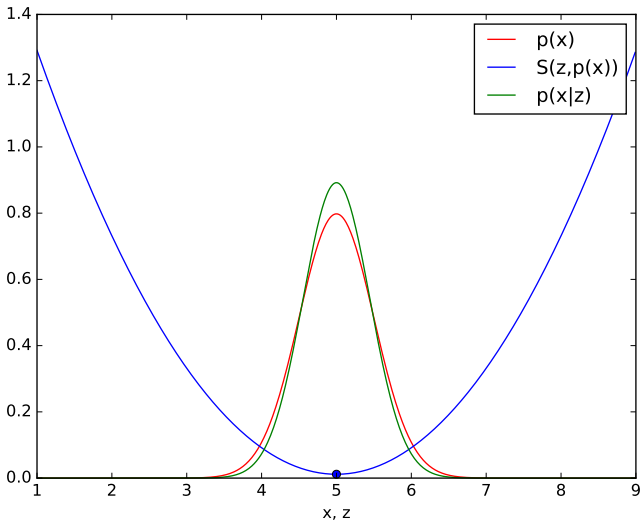
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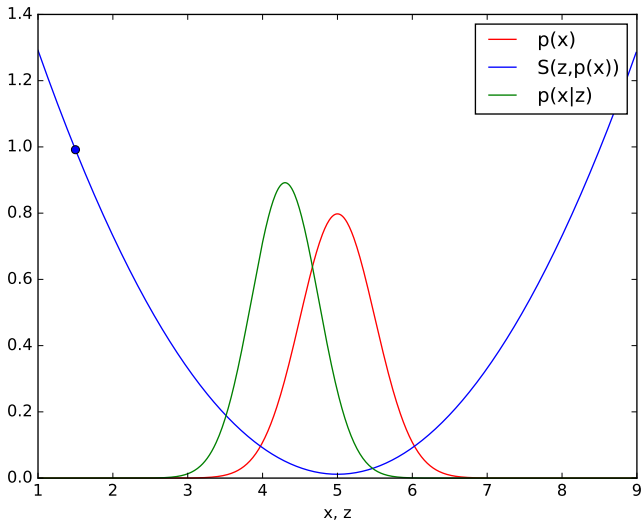
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# Quantifying Model Inconsistency

- Conflict between whole model and evidence:

$$C = \sum_i S_i$$

- What level of conflict is acceptable?
  - Calculate  $\mathcal{E}[C]$  and  $\text{var}[C]$  using model
  - Assume Gaussian distribution
  - Calculate threshold  $C_{th}$  such that  $P[C \leq C_{th}] = x\%$



# Reducing Model Inconsistency

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- Factor relaxation
  - Introduce adjustable parameters  $\theta_i$
  - If  $\theta_i = \mathbf{0}$ , factor unchanged
  - As  $\theta_i$  increase, surprise decreases
- Relaxation for regression example:

$$z_i = x + \epsilon_i, \quad \epsilon_i \sim \mathcal{N}(0, (\sigma_z + \theta_i)^2)$$

- Relaxation cost:  $J(\theta)$ 
  - E.g.  $J(\theta) = \|\theta\|_1$



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- Problem formulation:
  - Minimise  $J(\theta)$  s.t.  $C \leq C_{th}$
  - Or: *find the cheapest consistent model*
- Minimisation process:
  - Calculate  $\frac{\partial C}{\partial \theta}$  using automatic differentiation
  - Use modified Newton's method



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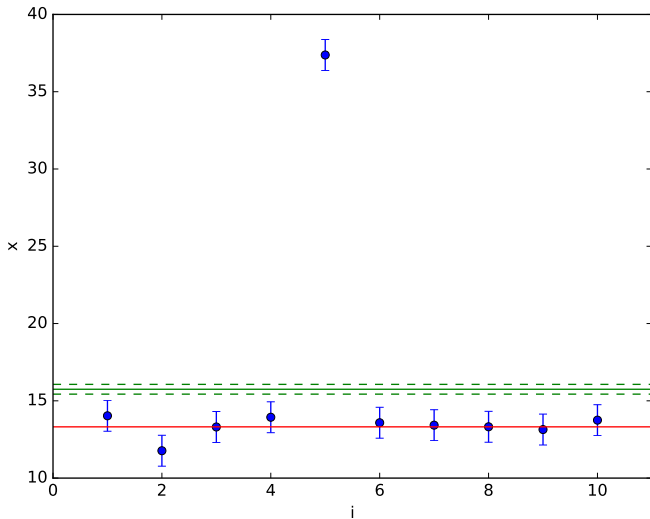
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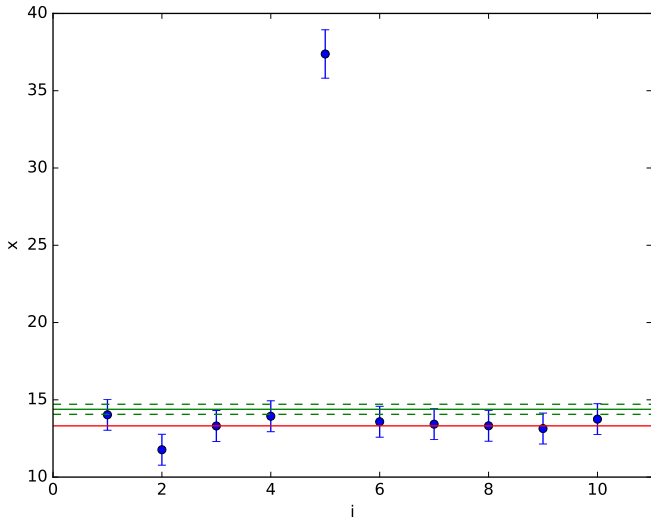
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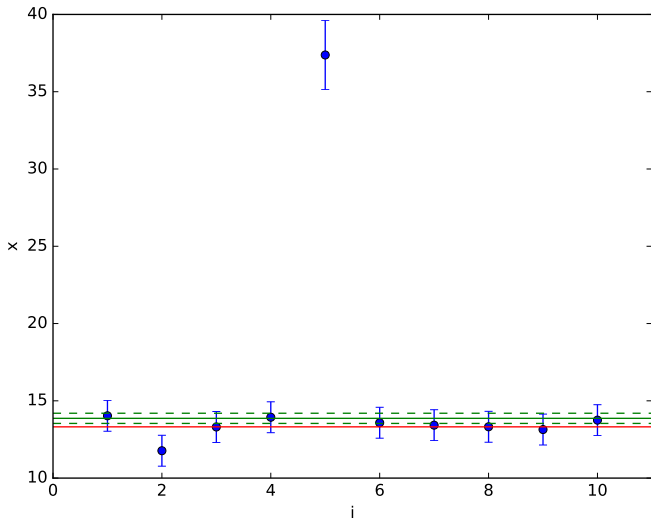
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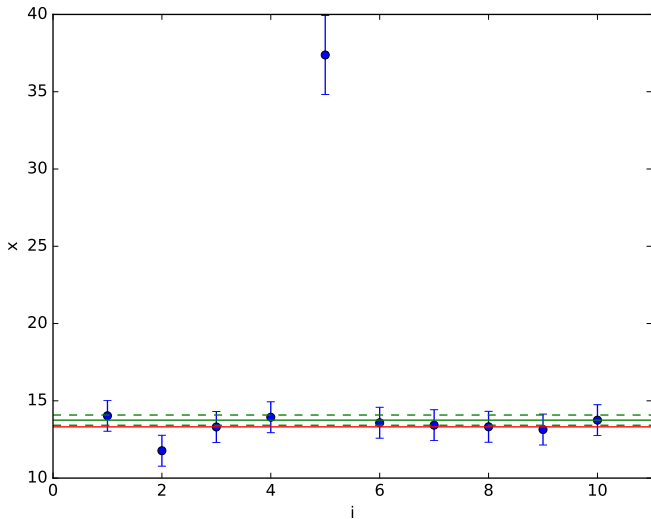
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But why do we not just use outlier detection and removal?



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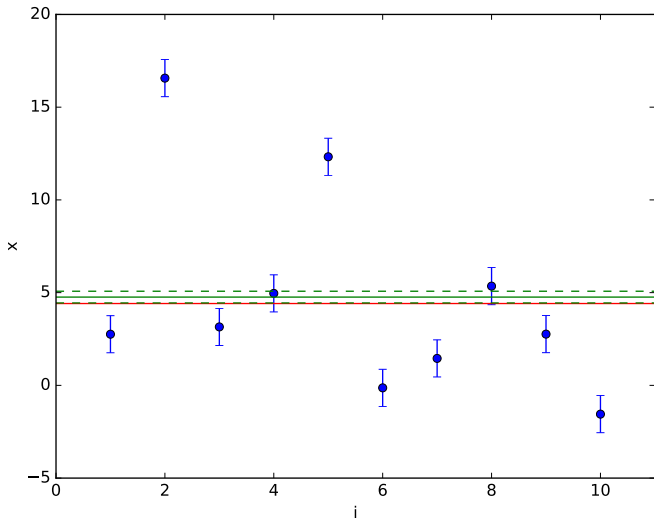
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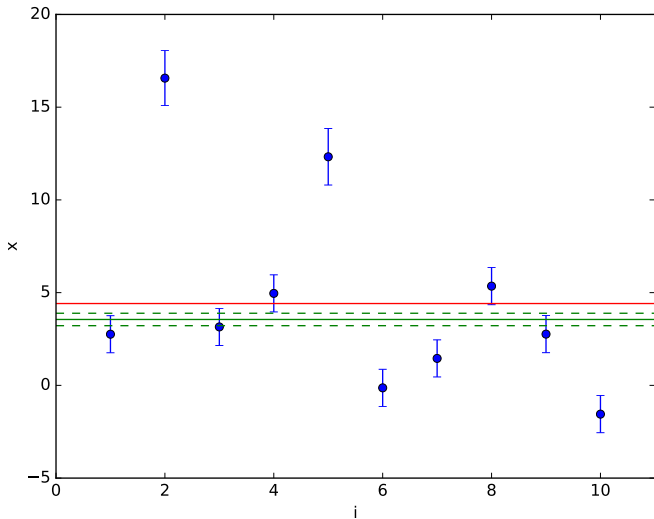
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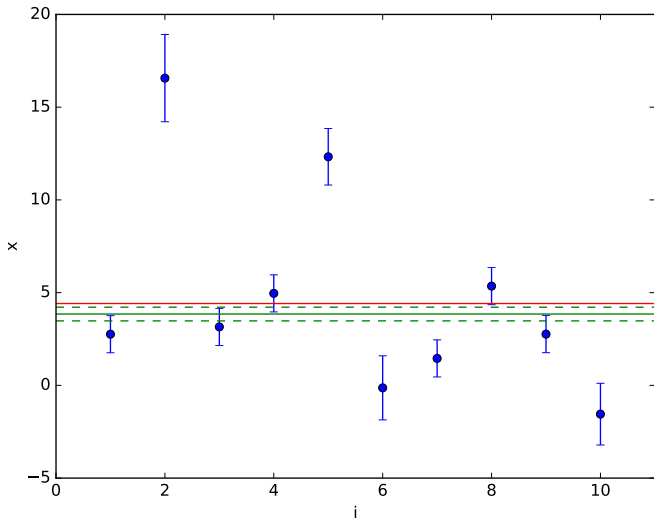
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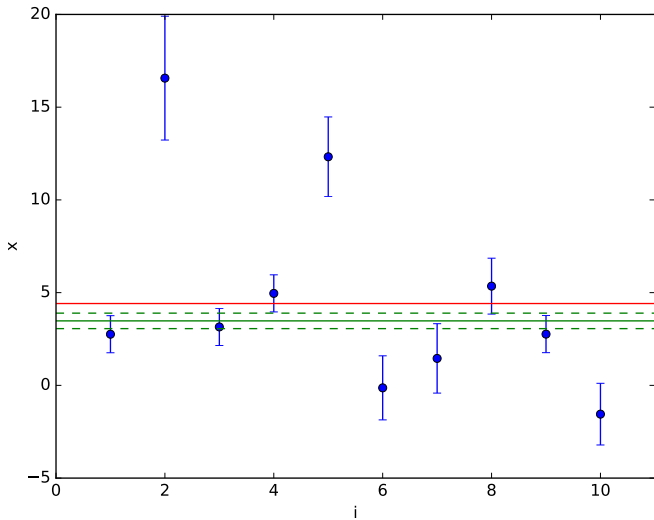
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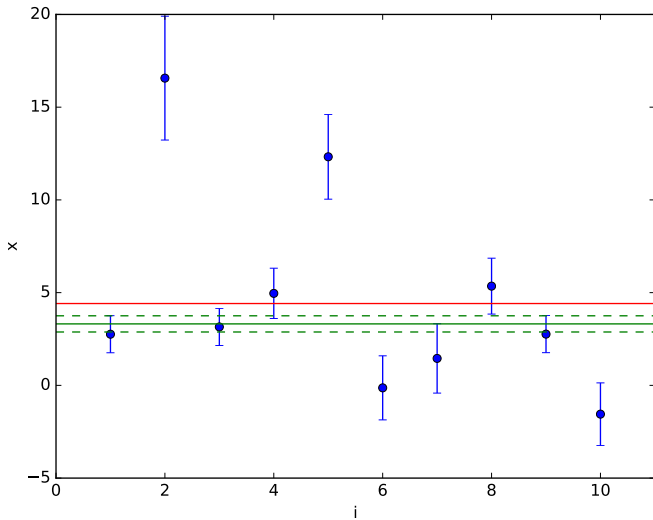
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- Summary:
  - Inconsistency between model and evidence cause problems
  - We propose a method to relax a model during inference to reduce model inconsistency
  - Which does not rely on complex, accurate modelling
  - This produces better wrong answers\*
- Characteristics of proposed method:
  - Fits into message passing for graphical models
  - Applicable to common continuous and discrete factors\*
  - Can be extended to general factors\*
  - Applicable to loopy networks\*
- Further ideas and work:
  - Test for various, realistic problems
  - Extend to loopy networks
  - Default reasoning